The Navarchos Fleet Management Platform

Dr. Ioannis Constantinou Istognosis CEO







Navarchos Features and Functionalities

- Cloud-based, scalable, highly available architecture based on
 microservices design pattern
- Efficient aggregation of multi-source data
- Facilitation of **complex event processing** over (potentially big) data warehousing
- Real-time, driver-centric notifications and recommendations algorithm for safe-driving and eco-driving
- Fleet-centric and driver-centric intelligent metrics and analytics
- Historical Vehicle Tracking System Data Analytics
- Routing optimization and route planning (scheduling) engine
- Navarchos FMS is currently installed in 30 small fleets in Cyprus supporting 180 vehicles



Navarchos Architecture













Navarchos Realtime Notifications

- Real time Notifications based on thresholds
 - Overspeed

Quick Lane change

• High Temperature

- High RPM
- Hard Cornering
- Hard Acceleration
- Hard Braking

Low Voltage

• Sharp Turn

• Long Idling

- Towing
- Real time notifications provided by CEP engine
 - A driver is in traffic jam. Notify other drivers in the area for the traffic jam in the specific route.
 - Weather is windy and/or rainy and/or snowy. Notify drivers in the area.



Navarchos Data Analytics and Driving Behavior Metrics

- More than **140 charts** of statistics and measurements
 - Individual driver analysis for **eco** and **safety** driving
 - Driver comparison for driver benchmarking
 - **Regression analysis** for investigating driver performance and providing recommendations







Navarchos Data Analytics and Driving Behavior Metrics

- Automatic points of interest (POI) detection
 - Spatial data Clustering using DBSCAN (density-based spatial clustering of applications with noise) algorithm.
- POI analytics
 - Histogram of time of arrival at each POI
 - Histogram of day of arrival at each POI
 - Histogram of stop duration at each POI
- Actual Route Vs Optimal Route
 - Distance covered (Km)
 - Trip duration (min)



Navarchos Map Matching and Trajectory Clustering Analytics

Trajectory Clustering based on Map Matching algorithm*

This algorithm works as follows:

- For each input GPS position, a number of map matching candidates within a certain radius around the GPS position is computed. The number of map matching candidates is computed based on the direction and the speed of the vehicle.
- The Viterbi algorithm is then used to compute the most likely sequence of map matching candidates.
- Thereby, the distances between GPS positions and map matching candidates as well as the routing distances between consecutive map matching candidates are taken into account.
- The **GraphHopper** routing engine is used to find candidates and to compute routing distances.
- The map matching trajectories are clustered using spatial algebra functions





Navarchos Routing Optimization and Scheduling Engine

USE CASE A

- X vehicles available having Xi capacity
- Y customers with Yi demand, Service Time.
- **Z warehouses** working time window.
- Products must be delivered to all customers within the time window of warehouse.
- Which is the minimum number of vehicles and their routes to cover the Y customers.

USE CASE B

- X vehicles available having Xi capacity
- Y customers with Yi demand, Ready Time, Due Time, Service Time.
- **Z warehouses** working time window.
- Products must be delivered to all customers within the time window of warehouse and each customers.
- Which is the minimum number of vehicles and their routes to cover the Y customers.



More questions about Navarchos?

Navarchos implementation is partially funded by Research Promotion

Foundation under <u>Restart Research 2016-2020 Programme</u> under the ENTERPRISES/0916/0072 agreement.

Project Coordinator: Dr. Ioannis Constantinou

t: +357 22 210031

m: +357 99 985432

e: ioannis@istognosis.com, info@navarchos.eu

Website: http://www.navarchos2.eu, https://www.istognosis.com

Linkedin: https://www.linkedin.com/groups/12174258/





